



Aalto University
School of Engineering



WISE-ACT – WG5

Scenario development

Claudio Roncoli

Assistant professor, Transportation Engineering

Key tasks

- T12: Develop and evaluate a number of scenarios of AVs deployment throughout Europe
- T13: Compare the results of simulation analyses across different localities
- T14: Develop a set of criteria and indicators which can inform policy makers about deployment of AV in a certain locality

Autonomous and Connected Transport scenarios evaluation based on simulation analysis

Authors:

- Nima Dadashzadeh (University of Portsmouth, UK)
- Arnor Elvarsson (ETH Zurich, Switzerland)
- Golam Morshed (University of Innsbruck, Austria)
- Serio Agriesti (Aalto University, Finland)
- Costas Antoniou (Technical University of Munich, Germany)
- Claudio Roncoli (Aalto University, Finland)
- Nikolas Thomopoulos (University of Surrey, UK)

Scenario development

- Simulation results are highly dependent on the scenario that is defined beforehand
- In this context, a scenario is defined by a set of parameters that affect simulation performances
- Different tools require different parameters
- Requiring assumptions on the ACT implementation
- Defining appropriate scenarios for each research question is crucial

Example of extreme scenarios



1 Full centralised automation and connectivity

Requires high investment in infrastructure. Prior to this, technological advancement is a prerequisite. The law has fully considered the exchange of data and communication. The automated vehicles are to drive relying on a central transmitter. Their sensors will have a secondary function. Increasingly separation of modes in urban areas.



2 Overnight technological shift

Vehicles will have to make do with the infrastructure in place. Technology will be expensive, so TNCs will offer AV services leading to increased traffic in cities.



3 Centralised last-mile system

There will be a centralised AV system set up, focusing mainly on serving the already-in-place mass transit system. AVs pick-up and drop-off mass transit users requiring to be driven the first/last mile.



4 Highway automation, but urban exile

Automated vehicles will be in full capacity on highways where they can be driven without interruption of less predictable traffic participants. Non-automated vehicles will be transitioned from highways. Automated vehicles will be transitioned out of cities, where urban residents will be in the focal point.

City locations

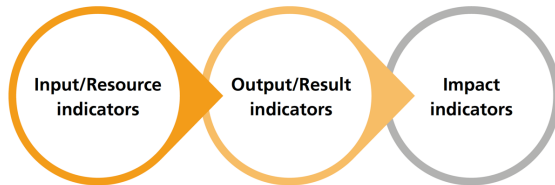


Simulation models and tools

- Heterogeneities in scenarios and research questions require different simulation tools.
Two main approaches:
 - Microscopic (traffic) simulations
 - Agent-based demand modelling
- Each simulation analysis differ by various features, including software, parameters settings, vehicle behavioural models, vehicle composition, study area, ...
- Need for establishing standards for building, calibrating, and validating traffic models of CAVs
- Feel free to look at the report for detailed results...

Criteria and indicators for ACT deployment

- Essential element of assessments and ultimate goal of scenarios and simulations
- Our framework:



| Type of indicators | Policy goal/objective/target | Indicators | Direction |
|---------------------------|--|-----------------------------|-------------------|
| Input/Resource indicators | <ul style="list-style-type: none"> – Measure input variable and simulation settings parameters – Minimise input – Minimise cost | Fleet size | Increase/decrease |
| | | Modal share | Increase/decrease |
| | | Peak hour demand | Decrease |
| | | Penetration rates | Increase |
| | | Service area | Increase |
| | | Travel cost | Decrease |
| | | Travel time | Decrease |
| | | Vehicle capacity | Increase |
| | | Vehicle recharge duration | Decrease |
| | | Vehicle range | Increase |
| | | Vehicle relocation time | Decrease |
| Output/Result indicators | <ul style="list-style-type: none"> – Measure the immediate (dis-) advantage of the project – Optimise the output – Maximise the utility | Dead kilometre travel | Decrease |
| | | Delay | Decrease |
| | | Total distance travelled | Increase/decrease |
| | | Value of travel time saving | Increase/decrease |
| | | Waiting time | Decrease |
| Impact Indicators | <ul style="list-style-type: none"> – Measures the indirect medium to long-term consequences. – Maximise and ensure societal sustainability – Long-term mobility decisions – Residential attractiveness – Improve transport equity and accessibility | Road capacity | Increase |
| | | Vehicle replacement rate | Increase |

Main takeaways

- Scenario developments and simulations are (the most effective) tools for quantitatively assessing impacts of ACT in future mobility systems
- Undesirable effects can be anticipated by wisely developing scenarios and simulations, evaluating appropriate indicators
- Need of increasing visibility of our results to policy makers and broader community to promote the design of sustainable ACT

Thank you!

claudio.roncoli@aalto.fi